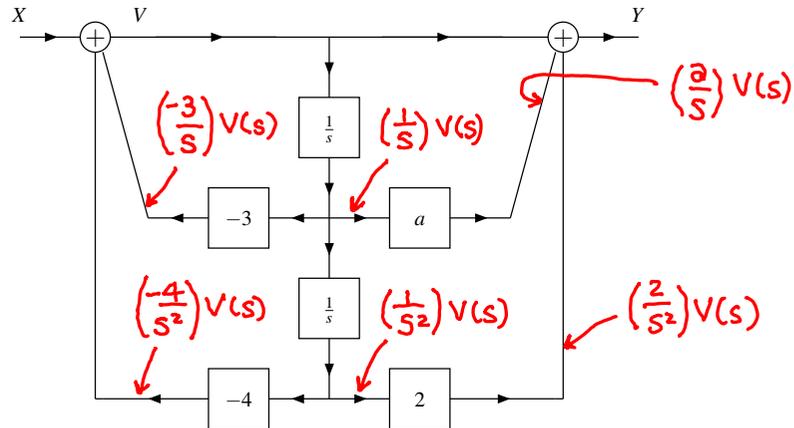


- 7.30 Consider the system \mathcal{H} with input Laplace transform X and output Laplace transform Y as shown in the figure. In the figure, each subsystem is LTI and causal and labelled with its system function, and a is a real constant.
- (a) Find the system function H of the system \mathcal{H} . (b) Determine whether the system \mathcal{H} is BIBO stable.

systematic approach to obtaining system function:

- 1) label system input and system output
- 2) label each adder output
- 3) write equation for each adder output and system output
- 4) combine equations to obtain system function



Short Answer. (a) $H(s) = \frac{s^2+as+2}{s^2+3s+4}$ for $\text{Re}(s) > -\frac{3}{2}$; (b) system is BIBO stable.

Answer (a,b).

From the system block diagram, we have:

$$Y(s) = V(s) + \left(\frac{a}{s}\right) V(s) + \left(\frac{2}{s^2}\right) V(s) \quad \text{and} \quad \textcircled{1}$$

$$V(s) = X(s) + \left(-\frac{3}{s}\right) V(s) + \left(-\frac{4}{s^2}\right) V(s). \quad \textcircled{2}$$

The preceding two equations can be rearranged to yield

$$\textcircled{3} \quad Y(s) = \left(1 + \frac{a}{s} + \frac{2}{s^2}\right) V(s) \quad \leftarrow \text{rearrange } \textcircled{1}$$

$$\textcircled{4} \quad X(s) = \left(1 + \frac{3}{s} + \frac{4}{s^2}\right) V(s). \quad \leftarrow \text{rearrange } \textcircled{2}$$

Thus, $H(s)$ is given by

$$\textcircled{*} \quad Y(s) = X(s) H(s) \Rightarrow H(s) = \frac{Y(s)}{X(s)}$$

$$\textcircled{*} \quad H(s) = \frac{Y(s)}{X(s)} = \frac{1 + a/s + 2/s^2}{1 + 3/s + 4/s^2} = \frac{s^2 + as + 2}{s^2 + 3s + 4}$$

Solving for the poles of $H(s)$, we obtain

$$\frac{-3 \pm \sqrt{9 - 4(1)(4)}}{2(1)} = -\frac{3}{2} \pm \frac{i\sqrt{7}}{2}.$$

Since the poles have negative real parts, the system is BIBO stable.