

**Example 4.5.** Consider a LTI system  $\mathcal{H}$  with impulse response

$$h(t) = u(t). \quad (4.23)$$

Show that  $\mathcal{H}$  is characterized by the equation

$$\mathcal{H}x(t) = \int_{-\infty}^t x(\tau) d\tau \quad (4.24)$$

(i.e.,  $\mathcal{H}$  corresponds to an ideal integrator).

*Solution.* Since the system is LTI, we have that

$$\mathcal{H}x(t) = x * h(t). \quad \textcircled{1}$$

Substituting (4.23) into the preceding equation, and simplifying we obtain

$$\begin{aligned} \mathcal{H}x(t) &= x * h(t) && \leftarrow \text{from } \textcircled{1} \\ &= x * u(t) && \leftarrow \text{substitute given function } h \\ &= \int_{-\infty}^{\infty} x(\tau) u(t - \tau) d\tau && \leftarrow \text{definition of convolution} \\ &= \int_{-\infty}^t x(\tau) u(t - \tau) d\tau + \int_{t^+}^{\infty} x(\tau) u(t - \tau) d\tau && \leftarrow \text{Split into two integrals} \\ &= \int_{-\infty}^t x(\tau) d\tau. && \leftarrow \text{second integral is 0} \end{aligned}$$

Therefore, the system with the impulse response  $h$  given by (4.23) is, in fact, the ideal integrator given by (4.24). ■