

Example 6.40 (Simple RL network). Consider the resistor-inductor (RL) network shown in Figure 6.26 with input v_1 and output v_2 . This system is LTI, since it can be characterized by a linear differential equation with constant coefficients. (a) Find the frequency response H of the system. (b) Find the response v_2 of the system to the input $v_1(t) = \text{sngt}$.

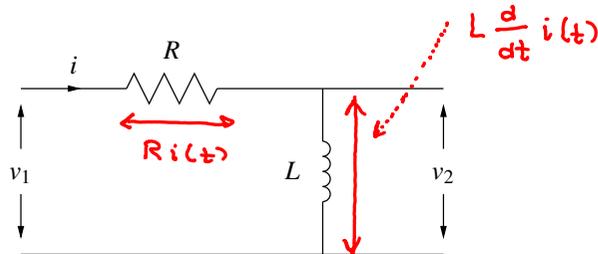


Figure 6.26: Simple RL network.

Solution. (a) From basic circuit analysis, we can write

$$v_1(t) = Ri(t) + L \frac{d}{dt} i(t) \quad \text{and} \quad (6.35)$$

$$v_2(t) = L \frac{d}{dt} i(t). \quad (6.36)$$

(Recall that the voltage v across an inductor L is related to the current i through the inductor as $v(t) = L \frac{d}{dt} i(t)$.) Taking the Fourier transform of (6.35) and (6.36) yields

$$\begin{aligned} V_1(\omega) &= RI(\omega) + j\omega LI(\omega) \\ &= (R + j\omega L)I(\omega) \quad \text{and} \end{aligned} \quad (6.37)$$

$$V_2(\omega) = j\omega LI(\omega). \quad (6.38)$$

From (6.37) and (6.38), we have

using time-domain differentiation property
 $\frac{d}{dt} x(t) \xleftrightarrow{\text{FT}} j\omega X(\omega)$

⊗ Since system is LTI,
 $v_2(\omega) = v_1(\omega) H(\omega) \Rightarrow$
 $H(\omega) = \frac{v_2(\omega)}{v_1(\omega)}$

$$\begin{aligned} H(\omega) &= \frac{V_2(\omega)}{V_1(\omega)} \\ &= \frac{j\omega LI(\omega)}{(R + j\omega L)I(\omega)} \\ &= \frac{j\omega L}{R + j\omega L}. \end{aligned} \quad (6.39)$$

⊗ Substitute (6.38) in numerator and (6.37) in denominator
 cancel I's

Thus, we have found the frequency response of the system.

(b) Now, suppose that $v_1(t) = \text{sngt}$ (as given). Taking the Fourier transform of the input v_1 (with the aid of Table 6.2), we have

$$V_1(\omega) = \frac{2}{j\omega}. \quad (6.40)$$

= F{sngt}(ω) from FT table

From the definition of the system, we know

↑ from ⊗

$$V_2(\omega) = H(\omega)V_1(\omega). \quad (6.41)$$

Substituting (6.40) and (6.39) into (6.41), we obtain

↑ $v_1(\omega)$ ↑ $H(\omega)$

$$\begin{aligned} V_2(\omega) &= \left(\frac{j\omega L}{R + j\omega L} \right) \left(\frac{2}{j\omega} \right) \\ &= \frac{2L}{R + j\omega L}. \end{aligned}$$

Substitute
 cancel factors of jω

Taking the inverse Fourier transform of both sides of this equation, we obtain

$$\begin{aligned}
 v_2(t) &= \mathcal{F}^{-1} \left\{ \frac{2L}{R + j\omega L} \right\} (t) \\
 &= \mathcal{F}^{-1} \left\{ \frac{2}{R/L + j\omega} \right\} (t) \\
 &= 2\mathcal{F}^{-1} \left\{ \frac{1}{R/L + j\omega} \right\} (t).
 \end{aligned}$$

Using Table 6.2, we can simplify to obtain

$$v_2(t) = 2e^{-(R/L)t}u(t).$$

taking inverse FT

divide numerator and denominator by L

linearity

from FT table

$$e^{-at}u(t) \xleftrightarrow{\text{FT}} \frac{1}{a + j\omega}$$

Thus, we have found the response v_2 to the input $v_1(t) = \text{sgn}t$. ■